

Fuzzy ARTMAP with Group Learning

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1. Introduction

Fuzzy ARTMAP achieves a synthesis of fuzzy logic and adaptive resonance theory (ART). In this study, we adapt an additional step called ‘‘Group Learning’’ to Fuzzy ARTMAP. This new algorithm is called Fuzzy ARTMAP with Group Learning (FAM-GL). The important feature of the group learning is that creating connections between similar categories. In other words, the FAM-GL learns not only categories but also its connections, namely, groups of the categories. We investigate the behavior of FAM-GL, and discuss the results.

2. Proposed Fuzzy ARTMAP

Fuzzy ARTMAP system incorporates two fuzzy ART modules, ART_a and ART_b , that are linked together through map field F^{ab} . ART_a is composed of F_1^a (input layer) and F_2^a (category layer). ART_b also has F_1^b and F_2^b . Input to ART_a and ART_b are in the complement code form, for ART_a , $\mathbf{I} = \mathbf{A} = (\mathbf{a}, \mathbf{a}^c)$, and for ART_b , $\mathbf{I} = \mathbf{B} = (\mathbf{b}, \mathbf{b}^c)$. For the map field (MF), let \mathbf{x}^{ab} denote the F_{ab} output vector, and let \mathbf{w}_j^{ab} denote the weight vector from the j th node to F^{ab} .

(FAM-GL1) \mathbf{A} and \mathbf{B} are inputted to F_1^a and F_1^b , respectively.

(FAM-GL2) For F_2^a , a winning category J is chosen by choice function T_J . J has maximal T_J . For ART_b , winning category K is chosen in the same way. Furthermore, for the group learning, the second-winning category, denoted by J_2 , is found. namely, T_{J_2} is the second largest.

(FAM-GL3) \mathbf{w}_j^{ab} and the out put vector \mathbf{y}^b of F_2^b are given to MF. \mathbf{x}^{ab} is calculated by

$$|\mathbf{x}^{ab}| \equiv |\mathbf{y}^b \wedge \mathbf{w}_j^{ab}|. \quad (1)$$

By Eq. (1), $\mathbf{x}^{ab} = 0$ if the prediction \mathbf{w}_j^{ab} is disconfirmed by \mathbf{y}^b . Such a mismatch event triggers an ART_a search for a better category, as follows.

(FAM-GL4) *Match Tracking*: At the start of each input presentation to ART_a , vigilance parameter ρ_a equals a baseline vigilance, $\bar{\rho}_a$. The map field vigilance parameter is ρ_{ab} . If

$$|\mathbf{x}^{ab}| < \rho_{ab} |\mathbf{y}^b|, \quad (2)$$

then ρ_a is increased until it is slightly larger than $|\mathbf{A} \wedge \mathbf{w}_j^a| / |\mathbf{A}|^{-1}$. When this occurs, ART_a search leads either to activation of another F_2^a node J , if no such node exists, to shutdown of F_2^a for the remainder of the input presentation. On the other hand, if

$$|\mathbf{x}^{ab}| \geq \rho_{ab} |\mathbf{y}^b|, \quad (3)$$

then follow step the (FAM-GL8).

(FAM-GL5) In this step, it is decided whether if a connection is formed. Eq. (3) is satisfied, a connection between the winning category J and the second-winning category J_2 is created; $C_{J,J_2} = 0$. The *age* of the connection between the winning category J and the second-winning category J_2 is set to zero ‘‘refresh’’ the age; $age_{J,J_2} = 0$. On the contrary, if Eq. (3) is not satisfied, the connection is not formed.

(FAM-GL6) The *age* of all categories which directly connect with the winning category J are increased one;

$$age_{J,j}^{new} = age_{J,j}^{old} + 1, \quad j \in N_J, \quad (4)$$

where N_J is set of categories which directly connect with J .

(FAM-GL7) The connections are removed, if their *age* exceeds a threshold value $AT(t)$;

$$C_{J,j} = 0, \quad age_{(J,j)} \geq AT(t), \quad (5)$$

$$AT(t) = AT_i(AT_f/AT_i)^{t/t_{max}}, \quad (6)$$

where t_{max} is the learning length, AT_i and AT_f is the initial value and the final value of AT , respectively. The steps from (FAM-GL1) to (FAM-GL7) are repeated for all the input data. Therefore, Fuzzy ARTMAP-GL makes connections or releases connections at each step.

(FAM-GL8) *Learning*: If Eq. (3) is satisfied, weight vectors \mathbf{w}_J^a , \mathbf{w}_K^b , \mathbf{w}_J^{ab} are updated, as follows.

$$\begin{aligned} \mathbf{w}_J^{a(new)} &= \beta_a (\mathbf{A} \wedge \mathbf{w}_J^{a(old)}) + (1 - \beta_a) \mathbf{w}_J^{a(old)} \\ \mathbf{w}_K^{b(new)} &= \beta_b (\mathbf{B} \wedge \mathbf{w}_K^{b(old)}) + (1 - \beta_b) \mathbf{w}_K^{b(old)} \\ \mathbf{w}_J^{ab(new)} &= |\mathbf{y}^b \wedge \mathbf{w}_J^{ab}| \end{aligned} \quad (7)$$

3. Simulation Results

We consider 2-dimensional input data of 300 points, which are random data. The learning results of Fuzzy ARTMAP and FAM-GL are shown in Fig. 1. Rectangles represent categories. From these results, we can see that the categories predicted being outside the circle are represented by dashed lines, and the categories predicted being inside are represented by straight lines in Fig. 1(a). Therefore input data are divided into two kinds of categories. However, we can not see an association between categories. On the other hand, in Fig. 1(b), we can see categories are divided into four groups by four marks. In other words, we can obtain two results of category learning and group learning by FAM-GL.

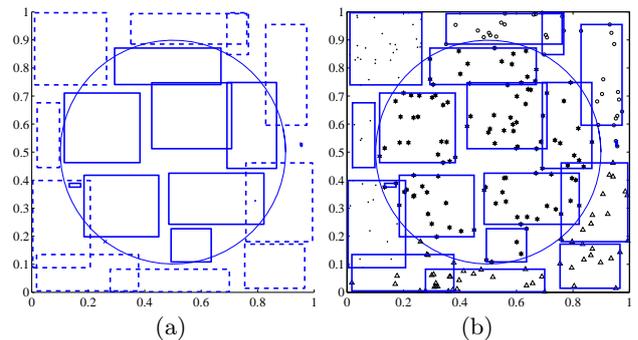


Figure 1: Simulation result. (a) Simulation result of the Fuzzy ARTMAP. (b) Simulation result of the FAM-GL.

4. Conclusions

In this study, we have adapted ‘‘Group Learning’’ to Fuzzy ARTMAP. We have investigated its behaviors with application to categorization of 2-dimensional input data, and confirmed the efficiency of FAM-GL.